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Newton said "I seem to have been only like a boy playing on the sea-shore and diverting myself in now and then finding a smoother pebble or prettier shell than ordinary, whilst the great ocean of truth lay a undiscovered before me."



The aim of these lectures is to show some of the beautiful pebbles and shells I know, which are discrete Painlevé equations.

§ 1 Introduction

In 1939, Shohat (Duke Math. J. 5 (2) (1939) 401-417) extended the study of orthogonal polynomials $\{\Phi_n(x)\}_{n=0}^\infty$ to the class with weight $\phi(x)$

$$\int_a^b \phi(x) \Phi_m(x) \Phi_n(x) dx = 0, \quad m \neq n, \quad m, n \in \mathbb{N}$$

s.t.

$$\phi(x) = \frac{1}{A(x)} \exp \left(\int_a^b \frac{B(x)}{A(x)} dx \right), \quad \text{with } A \neq 0 \text{ in } (a,$$

In the case $a = -\infty, b = \infty, \phi(x) = \exp(-x^2/4)$, he obtained

$$\lambda_{n+2} (\lambda_{n+1} + \lambda_{n+2} + \lambda_{n+3}) = n+1 \quad (1.1)$$

where λ_n is related to the 3-term recurrence relation

$$\Phi_n(x) - (x - c_n) \Phi_{n-1}(x) + \lambda_n \Phi_{n-2}(x) = 0, \quad n \geq 2$$

$\Phi_0 = 1, \Phi_1 = x - c_1$

Eqn (1.1) is a special case of what is now called the first discrete Painlevé equation: $(dP_1) \approx$

L4(2)

$$w_n (w_{n+1} + w_n + w_{n-1}) = \alpha n + \beta + \delta(-1)^n + \gamma w_n \quad (1-2)$$

where $\alpha, \beta, \gamma, \delta$ are consts.

The name comes from its continuum limit. Take $\delta=0$ and write $n =$

$$t = \varepsilon n, \quad w_n = \mu + \varepsilon^2 u(t), \quad u(t) \text{ assumed analytic}$$

$$\alpha = -\varepsilon^\alpha v, \quad \beta = -\frac{\gamma^2}{12}$$

then

$$w_{n\pm 1} = \mu + \varepsilon^2 u(t \pm \varepsilon)$$

$$= \mu + \varepsilon^2 \left\{ u(t) \pm \varepsilon u_t(t) + \frac{\varepsilon^2}{2} u_{tt}(t) + O(\varepsilon^3) \right\}$$

So we get from (1-2) :

$$(\mu + \varepsilon^2 u) \left(3\mu + 3\varepsilon^2 u + \varepsilon^4 u_{tt} + O(\varepsilon^6) \right)$$

$$= -\varepsilon^{\alpha-1} v t - \frac{\gamma^2}{12} + \gamma \mu + \gamma \varepsilon^2 u$$

Take

$$3\mu^2 = \gamma \mu - \frac{\gamma^2}{12}$$

$$3\mu^2 = \frac{\gamma^2}{6} - \frac{\gamma^2}{12} = \frac{\gamma^2}{12}$$

$$6\mu = \gamma$$

$$\Rightarrow \mu = \frac{\gamma}{6} \quad \text{ID}$$

and

$$\alpha-1 = 4$$

\Rightarrow

$$\mu u_{tt} + 3u^2 = -vt + O(\varepsilon^2)$$

Taking $\mu = -\frac{1}{2}$, $v = -\mu$, we get as $\varepsilon \rightarrow 0$

$$u_{tt} = 6u^2 + t$$

the first Painlevé eqn P_I , one of six classical Painlevé equations denoted $P_I - P_{VI}$.

$\mathcal{L}\phi$ (3)

Equation (1-2) is not the only discrete version of P_I .

For example: using the notation $w = w_n$, $\bar{w} = w_{n+1}$, $\underline{w} = w_{n-1}$

$$\circ \frac{\bar{z}}{\bar{w}+w} + \frac{z}{w+\underline{w}} + 2w^2 + t = 0$$

the "alternative d P_I "

where z is linear in n & (1)

$$\circ w_{n+1}, w_{n-1} = \frac{w_n - t_0 q^n}{w_n^2}, q \neq 0, 1 \quad (1-5)$$

q -discrete P_I or qP_I

where t_0, q are consts

are both integrable discrete versions of P_I .

The case $\delta \neq 0$ of Egn (1-2) has to be converted to a syst before attempting a continuum limit, i.e. define

$$w_{2k} = u_k$$

$$w_{2k+1} = v_k$$

$$\text{Case } n=2k: \quad u_k(v_k + u_k + v_{k-1}) = \frac{2\alpha k + \beta + \delta}{u_k} + \gamma \quad (1-3)$$

$$\text{Case } n=2k+1: \quad v_k(u_{k+1} + v_k + u_k) = \frac{(2\alpha k + \alpha + \beta - \delta)}{v_k} + \gamma \quad (1-4)$$

The system (1-3)-(1-4) is often called the "asymmetric" d P_I . (In Japan, it is called d P_S .)

Exercise: show that (1-3)-(1-4) has a continuum limit to

$$y_{tt} = 2y^3 + ty + a, \quad a \text{ is const}$$

which is P_{II} .



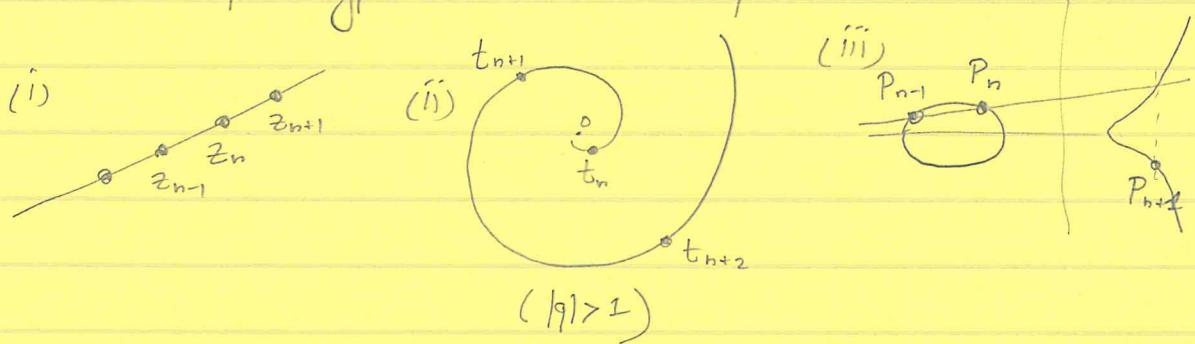
Lphi ④

In general, there are three types of discrete Painlevé equations (DPEs)

(i) additive-type = iterated on a straight line $z_n = \alpha n + \beta$
like (1.3)-(1.4)

(ii) multiplicative-or q-type = iterated on a spiral $t_n = t_0 q^n$
like (1.5)

(iii) elliptic-type = iterated on elliptic curves



Type (i) DPEs arise as recurrence relations from transformations of ODEs. Consider $P_{\text{IV}}(w, t; a, b)$:

$$w'' = \frac{w'^2}{2w} + \frac{3w^3}{2} + 4t w^2 + \omega(t^2 - a)w - \frac{b^2}{2w} \quad (1.6)$$

which has Bäcklund transformations : mapping

$$P_{\text{IV}}(w_n, t; a_n, b_n) \mapsto P_{\text{IV}}(w_{n+1}, t; a_{n+1}, b_{n+1})$$

with

$$a_n = -\frac{b}{2} - \frac{c_0}{2} + \frac{3c_1}{2}(-1)^n$$

$$b_n = n + c_0 + c_1(-1)^n \quad c_0, c_1, \text{consts.}$$

$$2w_n w_{n+1} = -w_n' - w_n^2 - 2t w_n + b_n \quad (1.7a)$$

$$2w_n w_{n-1} = w_n' - w_n^2 - 2t w_n + b_n \quad (1.7b)$$

Adding, we get

$$2w_n (w_{n+1} + w_n + w_{n-1}) = -4t w_n + 2b_n$$

which is (1-2) with $\gamma = -2t$, $\alpha = 1$, $\beta = c_0$, $\delta = c_1$.

Such transformations are simpler to understand in terms of reflections.
To see this, consider the symmetric form of P_{IV} :

$$\begin{aligned} \hat{f}_0 &= f_0(f_1 - f_2) + \alpha_0, & f_j &= f_j(s) \\ \hat{f}_1 &= f_1(f_2 - f_0) + \alpha_1, \\ \hat{f}_2 &= f_2(f_0 - f_1) + \alpha_2, \end{aligned}$$

where $f_0 + f_1 + f_2 = s$, $\alpha_0 + \alpha_1 + \alpha_2 = 1$.

Exercise: Eliminate f_0, f_1, f_2 and show that $f_0(s) = \mu w(t)$
with $t = \lambda s$ satisfies P_{IV} (eqn (4)) for some $\lambda, \mu, \alpha, \beta$.

The BTs can be written in terms of the operations:

$$\begin{aligned} s_i(\alpha_i) &= -\alpha_i & s_i(\alpha_j) &= \alpha_j + \alpha_i, \quad j = i \pm 1, \quad \pi(\alpha_j) = \alpha_{j+1} \\ s_i(f_i) &= f_i & s_i(f_j) &= \frac{f_j + \alpha_i}{f_i}, \quad j = i \pm 1, \quad \pi(f_j) = f_{j+1} \\ &&& \quad j \in \mathbb{N} \pmod{3}. \end{aligned}$$

See Noumi & Yamada (1993)

Okamoto (1986)

For example, the BT (1-7a) arises if we take

$$T = \pi \circ s_2 \circ s_1$$

$$\begin{aligned} \text{Check } T(\alpha_0) &= \pi \circ s_2(s_1(\alpha_0)) \\ &= \pi \circ s_2(\alpha_1 + \alpha_0) \\ &= \pi(s_2(1 + \alpha_2)) \\ &= \pi(1 + \alpha_0) \\ &= 1 + \alpha_0. \end{aligned}$$

Exercise: See also Tutorial 1, Q1. Show that $T(f_0)$ is related to
the BTs (1-7).

The operations s_j, π satisfy $s_j^2 = 1$, $(s_j s_{j+1})^3 = 1$, $\pi^3 = 1$,
 $\pi s_j = s_{j+1} \pi$.

These properties make the span

$W = \langle s_0, s_1, s_2 \rangle$ an affine Weyl (Coxeter) group or system,
and

$\tilde{W} = \langle s_0, s_1, s_2, \pi \rangle$ an extended affine Weyl group

The root system associated with $P_{\mathbb{X}}$ is $A_2^{(1)}$. (We explore this further in Lecture 2.)

Sakai (2001) showed \exists 22 classes of DPEs described by root sys.
 \Leftrightarrow initial value spaces

Type of Iteration	Type of Initial Value Space
Elliptic	$A_0^{(1)}$
Multiplicative	$A_0^{(1)*}, A_1^{(1)}, \dots, A_8^{(1)}, A_7^{(1)}$
Elliptic	$A_0^{(1)**}, A_1^{(1)*}, A_2^{(1)*}, D_4^{(1)}, \dots, D_8^{(1)}, E_6^{(1)}, \dots, E_8^{(1)}$

Each equation also has a symmetry group. To be a DPE, time iteration has to be a translation on the root lattice.

In these lectures, I will show how to construct

- the initial value space
- the symmetry group

of a given DPE and, conversely, given a parametrization of the initial value space, how to construct the corresponding DPE. I will focus on examples.

DPEs are pretty shells - but a lot can be understood about their solutions by understanding Sakai's theory.